

1 Melting and Solidification

$$Q = m[(T_{fus} - T^\ominus)C_{P,(s)} + \Delta_{fus}H + (T_{sh} - T_{fus})C_{P,(l)}]$$

$$T_{sh} \equiv T_{fus} + \text{superheat}$$

$$Y_c = \frac{m_{shipped}}{m_{poured}} = \frac{m_{casting(s)}}{m_{riser(l)} + m_{casting(l)} + m_{gating}}$$

1.1 Solidification Volume Change

$$\{T = T_{sh}\} : V_{(sh)} = \frac{m}{\rho_{(l)} + \Delta_{sh}\rho_{(l)}(T_{sh} - T)}$$

$$\{T = T_{fus}\} : V_{(l)} = \frac{m}{\rho_{(l)}}$$

$$\{T = T^\ominus\} : V_{(s)} = \frac{m}{\rho_{(s)}}$$

$$\Delta_T V = \frac{V_{(sh)} - V_{(s)}}{V_{(sh)}} \quad \Delta_{l \rightarrow s} V = \frac{V_{(s)} - V_{(l)}}{V_{(s)}} \quad V_{(s)} = V_{(l)}(1 + \Delta_{l \rightarrow s} V)$$

2 Chvorinov's Rule

$$M_c \equiv \left(\frac{V}{A_s}\right)_{metal} \quad \alpha_{mould} \equiv \frac{k}{\rho C_P} \quad \text{RoT: } M_{riser} \geq 1.1 M_{casting}$$

$$-l_2 = l_1 + l_1 \alpha (T_{fus} - T^\ominus)$$

2.1 Sand

$$t_s = B_s M_c^2$$

$$B_s \equiv \frac{\pi \alpha_{mould}}{4 k_{mould}^2} \rho_{metal(l)}^2 \frac{[\Delta_{fus}H + C_{P,metal(l)}(T_{pour} - T_{fus})]^2}{(T_{fus} - T^\ominus)^2}$$

2.2 Permanent

$$t_s = B_s M_c$$

$$B_s \equiv \rho_{metal(l)} \frac{\Delta_{fus}H + C_{P,metal(l)}(T_{pour} - T_{fus})}{h_{metal:mould}(T_{fus} - T_{0,mould})}$$

3 Cylindrical Risers

$$M_r \equiv \frac{V}{A_s} \quad A_s = 2\pi R^2 + \frac{2V}{R}$$

$$\text{RoT: } h = 2\varnothing, \text{ but } h = \varnothing \Rightarrow \eta = 1$$

$$M_{r, top} = \frac{\pi R^2 h}{\pi R^2 + 2\pi R} \Big|_{h=4R=2\varnothing} \geq \frac{2\varnothing}{9}$$

$$M_{r, side} = \frac{\pi R^2 h}{2\pi R^2 + 2\pi R} \Big|_{h=4R=2\varnothing} \geq \frac{\varnothing}{5}$$

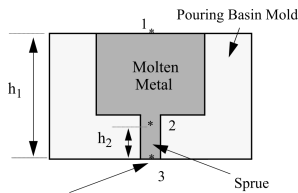
$$l_n \leq \frac{\varnothing_r}{2} \quad \varnothing_n \leq 1.2 l_n + 0.1 \varnothing_r$$

4 Steel Zones of Effect

$$EE = 2\delta \quad RE = 1.5\delta \quad ECE = \delta \quad MCE = 2EE = 4\delta$$

$$N_r = \frac{\ell - 2EE}{2RE + \varnothing_r} \text{ without chill}$$

5 Conservation of Mass, Energy, & Momentum

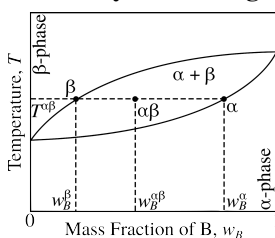


$$\hat{H} = z + \frac{v^2}{2g} + \frac{P}{\rho g} + \frac{\hat{E}}{g} \quad \dot{V}_1 \rho = \dot{V}_2 \rho \quad A_{\sigma 1} \vec{v}_1 = A_{\sigma 2} \vec{v}_2$$

$$\vec{v}_3 = \sqrt{2gh_1} \quad P_2 = P_3 - h_2 \rho \quad \vec{v}_2 = \sqrt{2g(h_1 - h_2)}$$

$$A_{\sigma 2} \vec{v}_2 = A_{\sigma 3} \vec{v}_3 \quad t_{fill} = \frac{V_{cavity}}{A_{\sigma 3} \vec{v}_3}$$

6 Binary Phase Diagram Lever Rule



$$w^\alpha(T^{\alpha\beta}) = \frac{w_B^{\alpha\beta} - w_B^\beta}{w_B^\alpha - w_B^\beta} \quad w^\beta(T^{\alpha\beta}) = \frac{w_B^\alpha - w_B^{\alpha\beta}}{w_B^\alpha - w_B^\beta}$$

7 Prerequisite Material

7.1 Statics

$$A = \iint dA \quad m = \iint_A \sigma dA$$

$$S_x = \iint_A y dA \quad S_y = \iint_A x dA \quad M_x = \iint_A y\sigma dA \quad M_y = \iint_A x\sigma dA$$

$$C_x = \frac{S_y}{A} \quad C_y = \frac{S_x}{A} \quad \bar{x} = \frac{M_y}{m} \quad \bar{y} = \frac{M_x}{m}$$

$$I_{Sx} = \iint_A y^2 dA \quad I_{Sy} = \iint_A x^2 dA \quad I_{Sz} = I_{Sx} + I_{Sy}$$

$$I_{Mx} = \iint_A y^2 \sigma dA \quad I_{My} = \iint_A x^2 \sigma dA \quad I_{Mz} = I_{Mx} + I_{My}$$

$$I_{Mx} = I_{M\bar{x}} + m\delta^2 \quad I_{Mx} = mk_x^2 \quad k_x = \sqrt{\frac{I_{Mx}}{A}}$$

$$I_{Pxy} = \iint_A xy dA \quad I_{Pxz} = \iint_A xz dA \quad I_{Pyz} = \iint_A yz dA$$

7.2 Dynamics

$$\vec{r} = I\vec{\alpha} \quad \vec{\tau} = \vec{r} \times \vec{F} \quad |\vec{\tau}| = |\vec{r}||\vec{F}|\sin\theta$$

$$W = \vec{\tau}\theta \quad E_k = \frac{1}{2}I\omega^2 \quad P = \vec{\tau}\omega$$

$$\vec{L} = \vec{r} \times \vec{P} \quad \vec{L} = I\vec{\omega} \quad \vec{\omega} \equiv \frac{\vec{r} \times \vec{v}}{r^2} \quad \vec{M} = \vec{r} \times \vec{F}$$

7.3 Mechanics of Materials

$$\sigma_e = \frac{\vec{F}}{A_{\sigma 0}} \quad \sigma = \frac{\vec{F}}{A_\sigma} = \sigma_e(1 + \epsilon_e)$$

$$\epsilon_e = \frac{\Delta \ell}{\ell_0} \quad \epsilon = \ln \frac{\ell}{\ell_0} = \ln(1 + \epsilon_e)$$

$$E = \frac{\sigma}{\epsilon_e} = \frac{\vec{F}\ell_0}{A_\sigma \Delta \ell}$$

$$\nu = -\frac{\epsilon_{transverse}}{\epsilon_{axial}}$$

$$G = \frac{\tau_{xy}}{\gamma_{xy}} = \frac{\vec{F}\ell_0}{A_\sigma \Delta x} = \frac{E}{2(1+\nu)}$$

$$K = -V_0 \frac{dP}{dV} = \rho_0 \frac{dP}{d\rho}$$

$$K_I = Y\sigma\sqrt{\pi\ell_{crack}}$$

7.4 Selected Nomenclature

C	Centroid	m
E	Young's modulus	Pa
G	Shear modulus	Pa
I_{Sx}	Moment of area (2 nd) / area mt. of inertia	m ⁴
I_{Mx}	Moment of mass (2 nd) / mass mt. of inertia	kg m ²
I_{Pxy}	Product moment of inertia	m ⁴
K	Bulk modulus	Pa
K_I	Fracture toughness, plane-strain	Pa m ^{1/2}
k	Radius of gyration	m
M_x	Moment of mass (1 st)	kg m
\vec{M}	Moment, bending	N m
S_x	Moment of area (1 st)	m ³
\bar{x}	Centre of mass	m
Y	Geometric factor	-
γ_{xy}	Shear strain	-
ϵ_e	Strain, engineering	-
ϵ	Strain, true	-
ν	Poisson's ratio	-
σ_e	Stress, engineering	Pa
σ	Stress, true	Pa
τ_{xy}	Shear stress	Pa

References

K. Rundman, *Principles of Metal Casting*. Houghton, MI, USA: Michigan Technological University.
<https://engineeringstatics.org/>